

L Number	Hits	Search Text	DB	Time stamp
-	57	((steven with schulz) or (nitinkumar with patel) or (james with nagashima) or (seung with ki with sul) or (bon with ho with bae)).in.	USPAT; US-PGPUB; EPO; JPO	2004/08/27 15:16
-	17	((steven with schulz) or (nitinkumar with patel) or (james with nagashima) or (seung with ki with sul) or (bon with ho with bae)).in.) and ((low or high) with speed)	USPAT; US-PGPUB; EPO; JPO	2004/08/27 15:17
-	10	((steven with schulz) or (nitinkumar with patel) or (james with nagashima) or (seung with ki with sul) or (bon with ho with bae)).in.) and ((low or high) with speed)) and (stator with current) and (flux with position)	USPAT; US-PGPUB; EPO; JPO	2004/08/27 15:20
-	144	(motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position)	USPAT; US-PGPUB; EPO; JPO	2004/08/31 12:42
-	17	((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position)) and ((high adj speed) same (flux with position))	USPAT; US-PGPUB; EPO; JPO	2004/08/31 13:23
-	37	(motor with control\$4) and ((low adj speed) with (rotor near2 position)) and ((high adj speed) with (rotor near2 position))	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:08
-	32	((motor with control\$4) and ((low adj speed) with (rotor near2 position)) and ((high adj speed) with (rotor near2 position))) not (((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position)) and ((high adj speed) same (flux with position))) not ((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position))	USPAT; US-PGPUB; EPO; JPO	2004/08/31 13:25
-	32	((motor with control\$4) and ((low adj speed) with (rotor near2 position)) and ((high adj speed) with (rotor near2 position))) not (((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position)) and ((high adj speed) same (flux with position))) not ((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position))) not (318/\$.ccls. and (((low or zero) and high) adj speed) and (stator with current) and (flux with position) )	USPAT; US-PGPUB; EPO; JPO	2004/08/31 13:26
-	38	((low adj speed) and (high adj speed) and (rotor near2 position)).ab.	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:44
-	31	((low adj speed) and (high adj speed) and (rotor near2 position)).ab.) not (((motor with control\$4) and ((low adj speed) with (rotor near2 position)) and ((high adj speed) with (rotor near2 position))) not (((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position)) and ((high adj speed) same (flux with position))) not ((motor with control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position))) not (318/\$.ccls. and (((low or zero) and high) adj speed) and (stator with current) and (flux with position) ))	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:23
-	0	gopinath adj observer	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:33
-	370	gopinath	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:24
-	44	gopinath and motor and control\$4	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:25
-	24	gopinath with observer	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:40
-	2	(gopinath with observer) not (gopinath and motor and control\$4)	USPAT; US-PGPUB; EPO; JPO	2004/08/31 14:34